

Vision Transformer

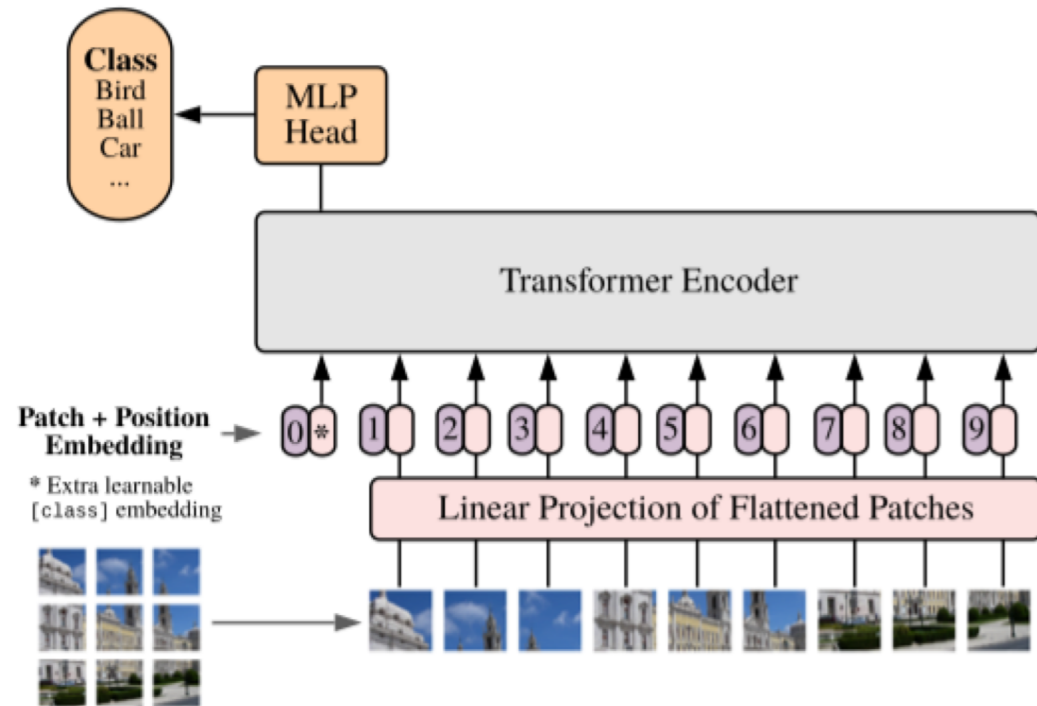
Yangtao Wang
James Crowley

Outline



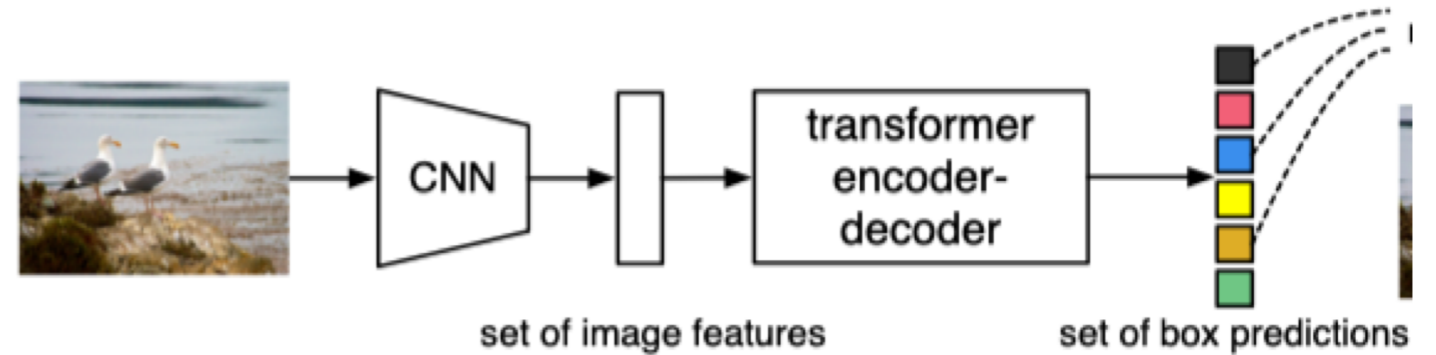
- Introduction
- Embeddings
 - Image embeddings
 - Positional embeddings
- Efficient attention mechanism
- Self-supervised method

Vision Transformer (ViT)



Only encoder

DETR

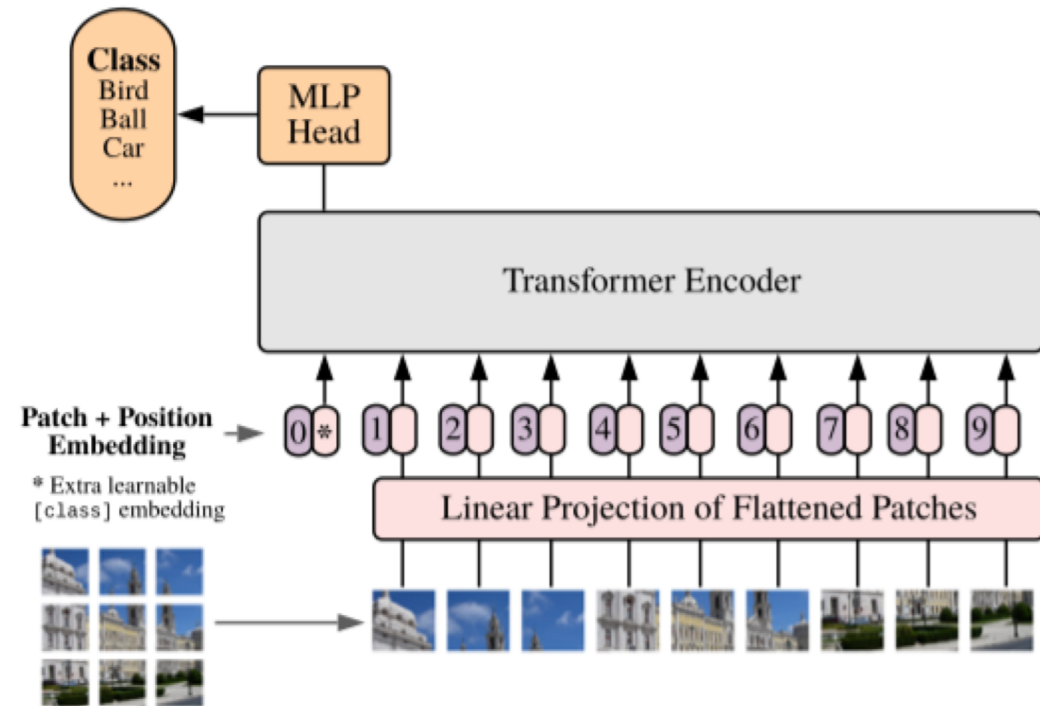


Encoder-decoder

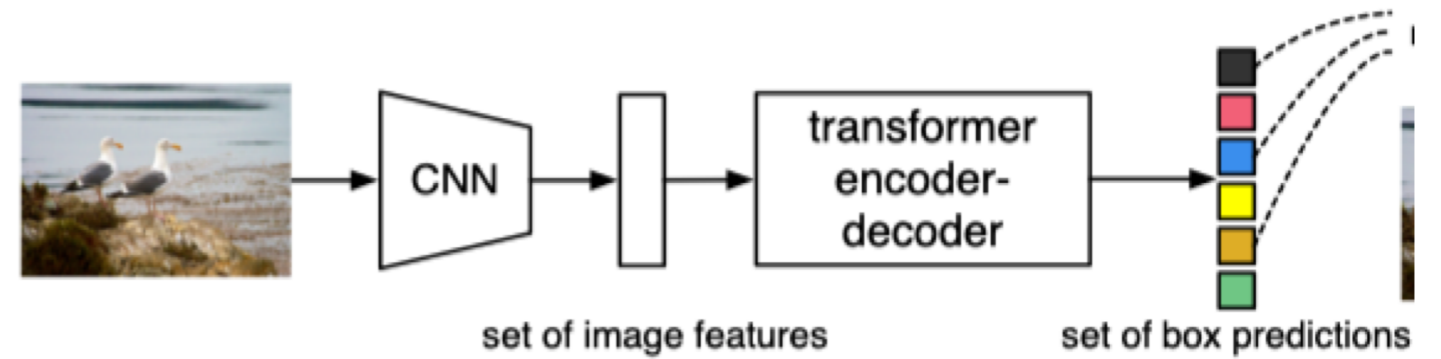
Classification: ViT[1], DeiT, PVT, MsViT, Swin-T
 Object detection: DETR[2], deformable DETR
 Object detection: PVT
 Tracking: TransCenter, ...
 Segmentation: DINO

[1]Dosovitskiy, A., Beyer, L., Kolesnikov, A., Weissenborn, D., Zhai, X., Unterthiner, T., Dehghani, M., Minderer, M., Heigold, G., Gelly, S., et al. (2020). An image is worth 16x16 words: Trans
 [2]Carion, N., Massa, F., Synnaeve, G., Usunier, N., Kirillov, A., & Zagoruyko, S. (2020, August). End-to-end object detection with transformers. In *European Conference on Computer Vision* (p

Vision Transformer (ViT)



DETR



Method 1: Splitting raw image into patches of 4x4, 8x8, 16x16, 32x32.

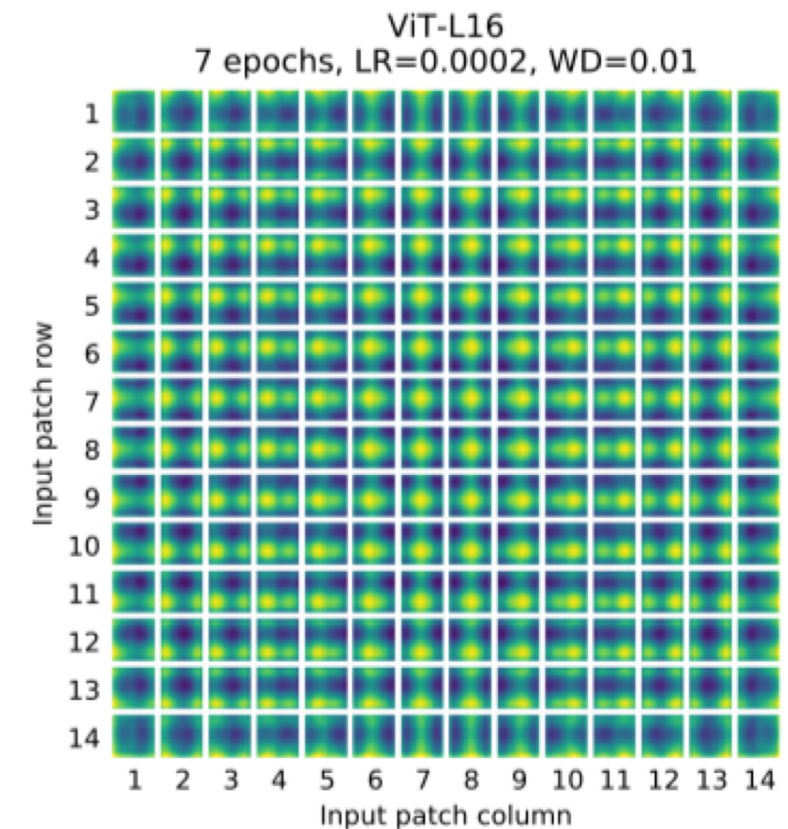
Method 2: Using CNN feature map.

- [1]Dosovitskiy, A., Beyer, L., Kolesnikov, A., Weissenborn, D., Zhai, X., Unterthiner, T., Dehghani, M., Minderer, M., Heigold, G., Gelly, S., et al. (2020). An image is worth 16x16 words: T
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- 1) **Learnable absolute 1D positional embeddings (ViT, DeiT[3])**
 Encode the inputs as a sequence of patches in the raster order.

- 2) **Learnable 2D positional embeddings (MsViT[4])**
 Encode the inputs as a grid of patches in two dimensions.

- 3) **Relative positional Embeddings (SwinT[5])**
 Encode the relative distance between patches.



$$\text{Attention}(Q, K, V) = \text{SoftMax}(QK^T / \sqrt{d} + B)V,$$

[3] Touvron, H., Cord, M., Douze, M., Massa, F., Sablayrolles, A., and Jégou, H. (2020). Training data-efficient image transformers & distillation through attention. arXiv preprint arXiv:2019.12.12.4318.

[4] Zhang, P., Dai, X., Yang, J., Xiao, B., Yuan, L., Zhang, L., and Gao, J. (2021). Multiscale vision longformer: A new vision transformer for high-resolution image encoding. arXiv preprint arXiv:2103.14920.

[5] Liu, Z., Lin, Y., Cao, Y., Hu, H., Wei, Y., Zhang, Z., Lin, S., and Guo, B. (2021). Swin transformer: Hierarchical vision transformer using shifted windows. arXiv preprint arXiv:2103.14920.

Different adding strategies:

- 1) Add positional embeddings to the inputs before feeding the inputs to the Transformer encoder. (e.g. ViT, DeiT)
- 2) Learn and add positional embeddings to the inputs at the beginning of each layer (e.g. PVT[6])
- 3) Add a learned positional embeddings to the inputs at the beginning of each layer (shared between layers).

Pos. Emb.	Default/Stem	Every Layer	Every Layer-Shared
No Pos. Emb.	0.61382	N/A	N/A
1-D Pos. Emb.	0.64206	0.63964	0.64292
2-D Pos. Emb.	0.64001	0.64046	0.64022
Rel. Pos. Emb.	0.64032	N/A	N/A

Table 8: Results of the ablation study on positional embeddings with ViT-B/16 model evaluated on ImageNet 5-shot linear.

[6] Wang, W., Xie, E., Li, X., Fan, D.-P., Song, K., Liang, D., Lu, T., Luo, P., and Shao, L. (2021). Pyramid vision transformer: A versatile backbone for dense prediction without

Problem for fixed size embeddings

Problem: If we want to fine-tune the model on higher resolution images, the pre-trained position embeddings may no longer be meaningful.

Method 1: Performing a 2D interpolation(bicubic) of the pre-trained position embeddings, according to their location in the original image, while keeping the patch size the same.

Method 2: Conditional Positional encoding (CPE[7])

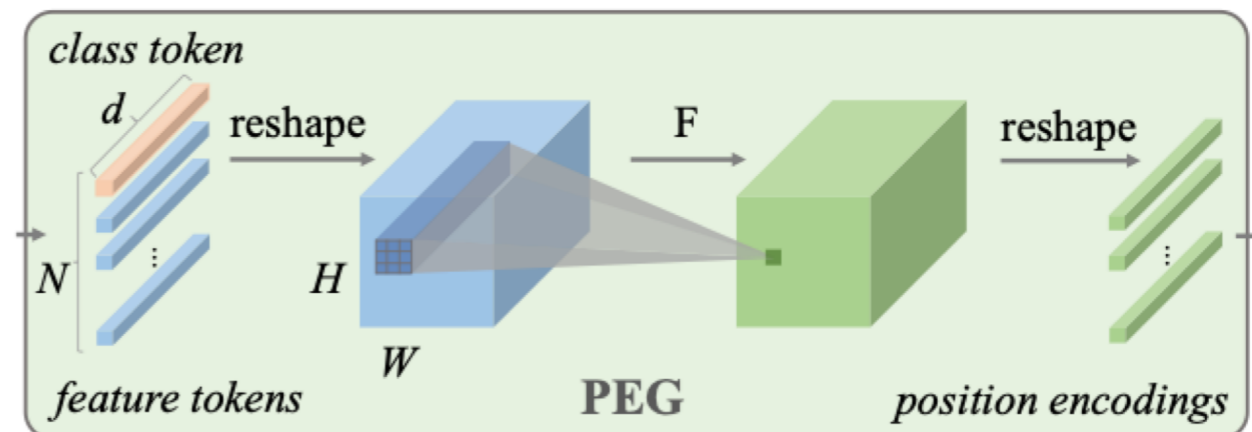
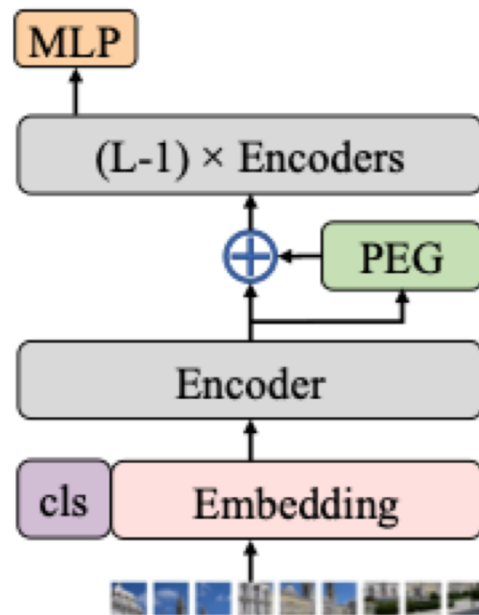
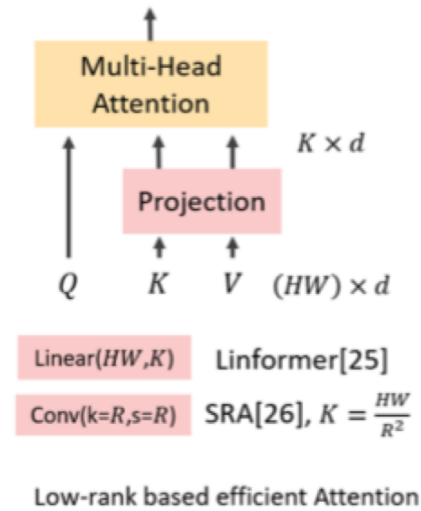


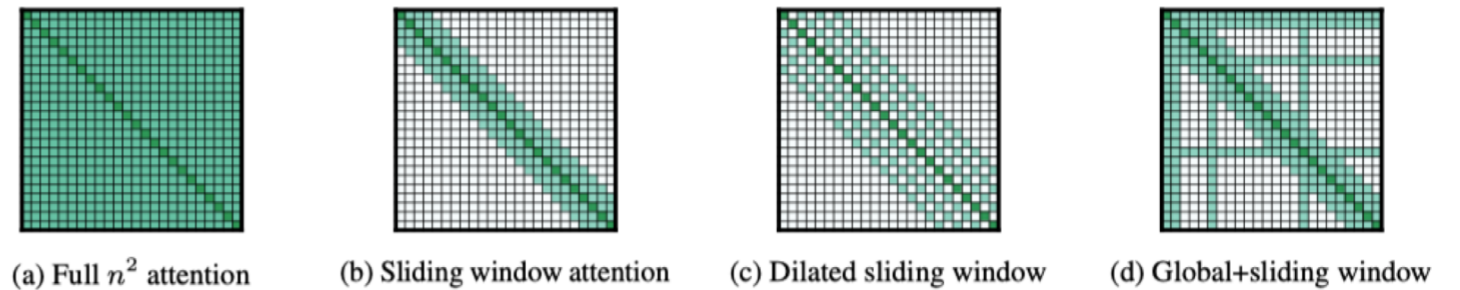
Figure 2. Schematic illustration of Positional Encoding Generator (PEG). Note d is the embedding size, N is the number of tokens. The function \mathcal{F} can be depth-wise, separable convolution or other complicated blocks.

Efficient attention mechanism

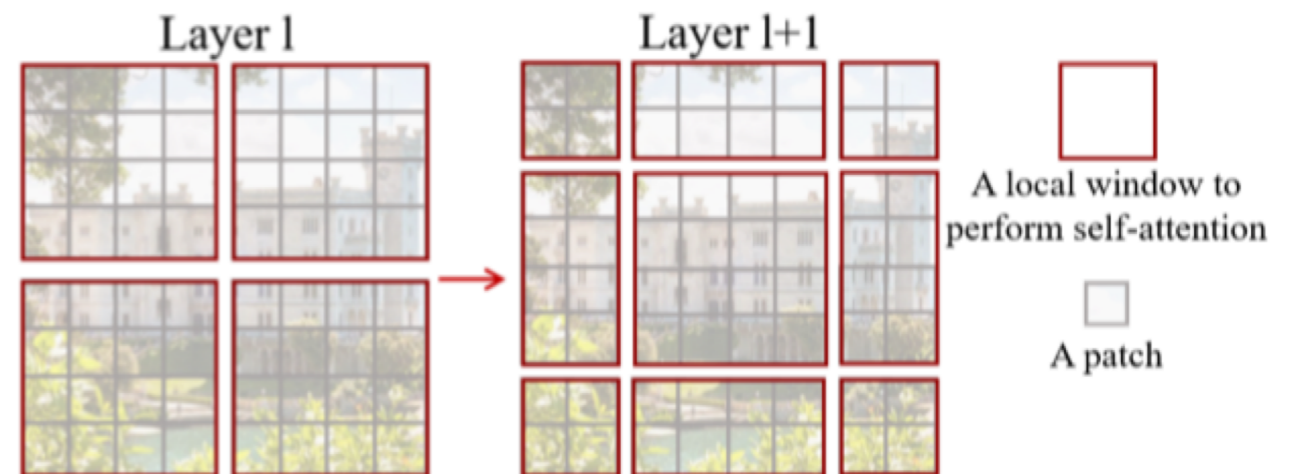
1) Low rank based method: PVT[6]



2) Sparse attention mechanism:
Axial transformer, Longformer[8]



3) Shifted window attention:
Swin Transformer[5]



Self-supervised learning

1) BERT like strategy: SiT[9]

Task 1: Image Reconstruction (Inspired by MLM)

Random drop, random replacement, colour distortion, blurring, grey-scale

Task 2: Rotation Prediction

Rotate image by $0^\circ, 90^\circ, 180^\circ, 270^\circ$, classify the rotation by rotation token

Task 3: Contrastive learning (Inspired by next sentence prediction)

Given half of the negative samples from other image and adopt cosine similarity by using contrastive



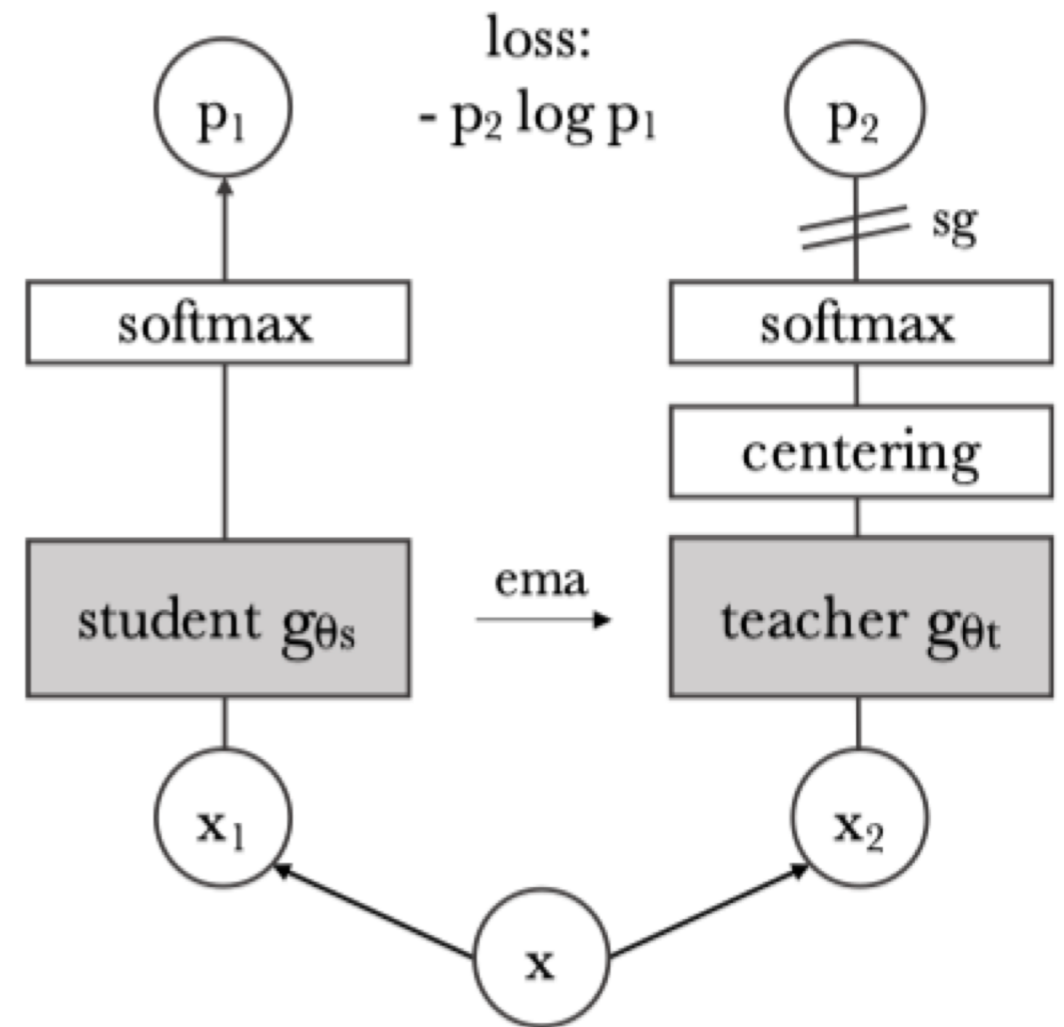
[9] Atito, S., Awais, M., & Kittler, J. (2021). SiT: Self-supervised vision Transformer. *arXiv preprint arXiv:2104.03602*.

Self-supervised learning

- 1) Student-teacher based strategy: DINO[10]
Dynamic teacher network updated
by previous student weights with momentum encoder



Figure: Self-attention from a Vision Transformer with 8x8 patches trained with no supervision



Transformer survey papers

- 1) Khan, S., Naseer, M., Hayat, M., Zamir, S. W., Khan, F. S., & Shah, M. (2021). Transformers in Vision: A Survey. *arXiv preprint arXiv:2101.01169*.
- 2) Tay, Y., Dehghani, M., Bahri, D., and Metzler, D. (2020b). Efficient transformers: A survey. *arXiv preprint arXiv:2009.06732*.

Thank you